

HENSOLDT **SETAS**

See Through Armour System

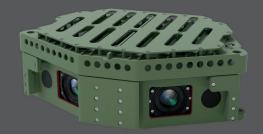
SETAS is a day and night high performance local area observation system for any type of armoured vehicle.

Main Benefits

- The user can stay in safety within the vehicle but with a high degree of situational awareness
- The visual sensor is capable of the recognition of a person at a distance of more than 300 m
- Using a head-mounted display as HMI, a crew member inside can virtually "see through" the armour
- Individual and independent view (scalable) for up to 8 crew members – this allows each crew member to observe its important region of interest

Capabilities

- 360° close area observation under hatch by day and night
- Threat identification and tracking
- Data exchange with other vehicle sytems



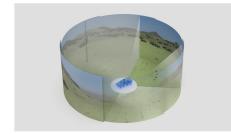


HENSOLDT SETAS

This high resolution electro optical vision system gives each crew member the possibility to stay secure under hatch without losing full visual situational awareness, 360° around the vehicle. Threats like snipers or RPGs can be detected within their operating range. The high vertical field of view makes the system superior for environments

like the urban canyon and for threats from above. The modular system accommodates two powerful sensor systems: very high resolution colour daylight cameras and uncooled thermal imagers. The mission-approved uncooled thermal imager is already mounted on several military vehicles worldwide.

Applications			Key Feature	Key Features			
 24/7 close area observation 360° around vehicle under armour with real-time image stitching of all the surrounding cameras Threat identification and tracking Data exchange with other vehicle sytems Individual and independent view for up to 8 operators each with their own area of interest 			 Very high resolution Intuitive HMI Modular system configuration Open architecture (NGVA HW ready) Ruggedized according MIL-STDs Low latency <100 ms 				
Preliminary Performance Data*			Options				
System Data			Cleaning systems				
Field of view	360° / 77° (daylight) and 48° (thermal) (+ option hemispherical camera)		 Ballistic protection cover Moving Target Indication (MTI) Object tracking 				
Thermal camera				and display unit			
Wavelength	LWIR (8 to 14 µm)		Digital image stabilisationHemispherical camera to cover the area above the vehicle				
Field of view	64° (h) / 48° (v)						
Daylight camera			 Augmented Reality, also with external data (e.g. data annotation) Integration of existing vehicle cameras 				
Detector	Colour CMOS		Handover of data to existing sight systems				
Field of view	95° (h) / 77° (v)		Automatic alert broadcast into the vehicle networkImage fusion (thermal and visual)				
Electrical Data*			Environmer	tal Conditions*			
Power supply	24V DC nominal		Operating temperature		according MIL-STD-810 E		
Interface	NGVA HW ready; Ether	net; 3G-SDI,	Environmental tests		according MIL-STD-810 G		
Over all dimensions*	ICM for Forward and Backward View	ICM for Let Right View		CIPU		2 x PSU	
Dimensions in mm (W x H x D)	preliminary 414 x 160 x 304	preliminary 480 x 160 x	314 mm	preliminary 426 x 280 x 490		preliminary 300 x 110 x 260	
Weight	approx. 11 kg	approx. 12 k	(g	approx. 35 kg		approx. each 11 kg	
Range Performance*/**				Theoretical Overall System			
Sensor	Thermal	Daylight		Power Consumption		Typical: 400 W (PRELIMINARY) Max: 1 kW (Peak Load, PRELIMINARY)	
Person detection	450 m	900 m					
Person recognition	150 m	300 m					
Person identification	80 m	150 m		IP class of the		IP68 / IP66K (ICMs)	
*subject to technical mod	ifications; data based on curre	ent development l	evel	housing/connectors		IP54 (CIPU)	



** MRC (Minimum resolvable contrast) Methode

Seamless 360° Situational Awareness



Integrated Camera Module



Integration of Threat-Sense by Pearson Engineering is possible – using Artificial Intelligence to identify ordnance